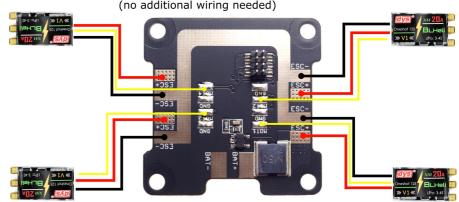
## FLYING LEM®N KIWI.F4V2

## Specification:

- -STM32F405 processor, 170MHz
- -low noise, vibration resistant MPU6000 gyro chip on SPI-bus
- -compatible with latest Betaflight
- -switching step-down 5V and 600mA current output, up to 6S input (not needed external 5V regulator)
- -12V/0.7A linear BEC for video line
- -LC filter on video line
- -SDCard slot for data logging
- -OSD (only for betaflight)
- -USB port independent of UART ports
- -programmable, hardware SBUS inverter
- -dedicated Spektrum Satellite connector with 3.3V output
- -buzzer driver
- -LED strip output
- -VBAT monitor
- -RSSI monitor
- -current monitor
- -BOOT button for simple flashing
- -DSHOT600 support
- -dedicated PDB with current sensor up to 160A (included!)

KIWI PDB have current sensor up to 160A Connected to FC through header connector (no additional wiring needed)



KIWI.F4 have three independent UART port. USB does not interfere with UART. Use UART1 to serial RC link (SBUS, DSMX, etc).

Set in configurator vbat scale to 57.

